

# Starting the Docker Container

Start the ROS Noetic docker container.

```
rkitect@gibsonhh:~$ docker start rosbag_container
```

It should already have the volumes set

- `rosbag_workspace:/root` - Contains all changes made to the ROS environment after initial pull
- `/mnt/taketwo/Web/nextcloud/data/rkitect/files/Documents/GI360/Ros Trials/AIA Conference/;/mnt/DataSets` - Contains the AIA Conference DataSet that I scanned

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