

Setting Up ROS

This process uses ROS Noetic because it was the latest version of ROS which still uses ROS1.

Once you're in the container bash, source the ROS Environment

```
source /opt/ros/noetic/setup.bash
```

Revision #2

Created 20 October 2024 20:00:29 by rkitect

Updated 20 October 2024 20:05:25 by rkitect